

Servo amplifier

mcDSA-E27XC-EtherCAT

Article number: 1513203

Certification:   *1



Picture similar

Technical data

Supply voltages		Functional safety	
Electronic supply voltage Ue* ²	9..30 V	Safety function refer safety manual	Safe Torque Off (STO)
Electronic current consumption@ Ue=24V* ³	typ. 100 mA	Safety Integrity Level (SIL)	up to SIL 3
Power supply voltage Up* ⁴	9..60 V	Performance Level (PL)	up to PL e
Output current		Sensor supply (Encoder)	
Max. output current	160 A	Output voltage	5 V
Continuous output current (certified UL/CE)* ⁵ @Up=24V	54 A	Max. output current	0.2 A
@Up=60V	49 A		
Continuous output current (not certified)* ⁶ @Up=24V with Heatsink (Art.No. 1511832)	65 A	Encoder	
	75 A	Type	sin / cos
Continuous output current (not certified)* ⁶ @Up=48V with Heatsink (Art.No. 1511832)	55 A	Signals	+Sin,-Sin,+Cos,-Cos
	65 A	Resolution	13 bit per sine period
		Input voltage	1 V peak-peak, differential
		Signal type	sine/cosine, analog, differential
PWM		Digital inputs	
Output voltage	100% Up	Number - digital inputs	6 (Din0..5)
PWM frequency	25, 32* ⁷ , 50 kHz	Low voltage	0.5 V
Mechanical		High voltage	8..30 V
Size LxWxH	111 x 100 x 55 mm	Notice	Din5 parallel with Dout2* ⁸
Weight	630 g	STO channels (STO-A..B)	
Environment		Low voltage	0.5 V
Protection class	IP20	High voltage	8..30 V
Ambient temperature (operation) (certified UL/CE)	-25..40 °C	Digital outputs	
Ambient temperature (operation) (not certified)	-25..70 °C	Number	3 (Dout0..2)
Ambient temperature (storage)	-25..85 °C	Continuous output current (certified UL/CE)	1 A
Rel. humidity (non-condensing)	5..90 %	Continuous output current (not certified)	1.5 A
CAN bus		Load Dout0..1	resistive, low inductive
Protocol	DS301	Load Dout2	resistive, inductive
Device profile	DS402	Output voltage	Electronic supply voltage Ue
Max. baudrate	1 Mbit/s	Signal type	positive switching
CAN specification	2.0B	Notice	Dout2 parallel with Din5
Galvanically isolated	yes	Analog inputs	
EtherCAT		Number	2 (Ain0..1)
Type	EtherCAT Slave	Signal type - Ain0	+/- 10 V, 12 Bit, differential
Physical layer	100 Base-Tx EtherCAT	Signal type - Ain1	+/- 10 V, 12 Bit, single ended
Bus controller	ET1100		
Max. baudrate	100 Mbit/s		
Number of ports	2xRJ45 (In,Out)		
Protocol	CoE (CANopen over EtherCAT)		

*1 The certified performance data must be observed (see UL Instruction Note and Safety Manual (CE))

*2 No reverse polarity protection, the destruction limit is at overvoltage of >= 33V or short-term peak voltage of 37V < 1s

*3 power amplifier switched off, 5V output (sensor supply) is free, STO active

*4 No reverse polarity protection, the destruction limit is at overvoltage of >= 80V

*5 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output active, RMS current: 54 A → 44 Aeff, 49 A → 40 Aeff

*6 connector cable with max. possible cable cross-section, PWM frequency 32 kHz (asymmetrical), ambient temperature 40 °C, I/O's and 5V output free, RMS current: 55 A → 45 Aeff, 65 A → 53 Aeff, 75 A → 61 Aeff

no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current

*7 default value

*8 Input voltage must not exceed Electronic supply voltage Ue

Additional technical data are available in mcManual.



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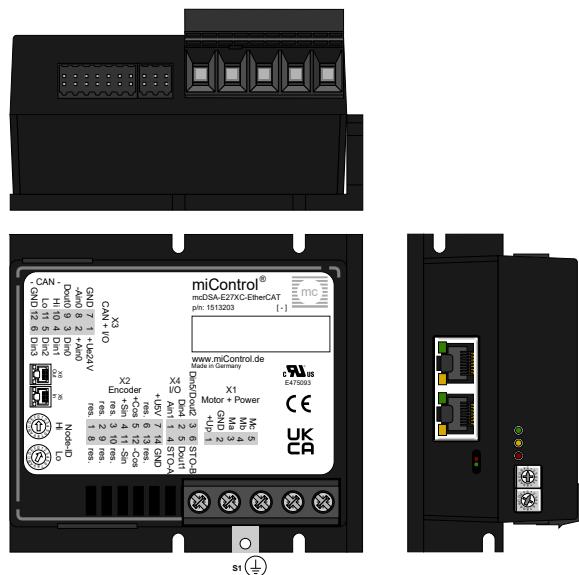
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Scheme



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Terminal assignment

X1	Motor	
1	+Up	Power supply voltage
2	GND	Ground for power supply voltage
3	Ma	Motor phase A
4	Mb	Motor phase B
5	Mc	Motor phase C
X2	Encoder	
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	+Cos	Encoder, plus cosine signal
6	res.	Reserved
7	+U5V	5V output voltage for sensor supply Sensors: encoder
8	res.	Reserved
9	res.	Reserved
10	res.	Reserved
11	-Sin	Encoder, minus sine signal
12	-Cos	Encoder, minus cosine signal
13	res.	Reserved
14	GND	Ground for sensor supply Notice: don't connect with system GND
X3	I/O's and CAN	
1	+Ue24V	Electronic supply voltage
2	+Ain0	Analog input 0, plus
3	Din0	Digital input 0
4	Din1	Digital input 1
5	Din2	Digital input 2
6	Din3	Digital input 3
7	GND	Ground for electronic supply voltage
8	-Ain0	Analog input 0, minus
9	Dout0	Digital output 0
10	CAN Hi	CAN High
11	CAN Lo	CAN Low
12	CAN GND	CAN Ground

X4	I/O's	
1	Ain1	Analog input 1
2	Din4	Digital input 4
3	Din5/Dout2	Digital input 5 / Digital output 2
4	STO-A	STO channel A
5	Dout1	Digital output 1
6	STO-B	STO channel B
S1	Screw (M4)	
-	FE	Functional earth
X5	EtherCAT - In port	
-	In	In
X6	EtherCAT - Out port	
-	Out	Out