Servo amplifier

mcDSA-E57-EtherCAT-HC

Article number: 1514628

Picture similar

Technical data

Supply voltages	
Electronic supply voltage Ue*1	9..30 V
Electronic current consumption@ Ue=24V*2	typ. 70 mA
Power supply voltage Up*3	9..60 V
Output current	
Max. output current	50 A
Continuous output current @ Up=24V*4	14.5 A
Continuous output current @ Up=48V*4	14.5 A
PWM	
Output voltage	100% Up
PWM frequency	25, 32*5, 50 kHz
Mechanical	
Size LxWxH	87 x 74 x 49 mm
Weight	226 g
Environment	
Protection class	IP20
Ambient temperature (operation)	-40..70 °C
Ambient temperature (storage)	-40..85 °C
Rel. humidity (non-condensing)	5..90 %
CAN bus	
Protocol	DS301
Device profile	DS402
Max. baudrate	1 Mbit/s
CAN specification	2.0B
Galvanically isolated	no
EtherCAT	
Type	EtherCAT Slave
Physical layer	100 Base-Tx EtherCAT
Bus controller	ET1100
Max. baudrate	100 Mbit/s
Number of ports	2xRJ45 (In,Out)
Protocol	CoE (CANopen over EtherCAT)

Sensor supply (Encoder)	
Output voltage	5 V
Max. output current	0.2 A
Encoder	
Type	sin / cos
Signals	+Sin,-Sin,+Cos,-Cos
Resolution	13 bit per sine period
Input voltage	1 V peak-peak, differential
Signal type	sine/cosine, analog, differential
Digital inputs	
Number - digital inputs	8 (Din0..7)
Low voltage	0..5 V
High voltage	8..30 V
Digital outputs	
Number	4 (Dout0..3)
Continuous output current	0.3 A
Load Dout0..2	resistive, low inductive
Load Dout3	resistive, inductive
Output voltage	Electronic supply voltage Ue
Signal type	positive switching
Analog inputs	
Number	3 (Ain0..2)
Signal type - Ain0..1	+/- 10 V, 12 Bit, differential
Signal type - Ain2 / PT1000	0..5 V, 12 Bit, single ended / PT1000

*1 No reverse polarity protection, the destruction limit is at overvoltage of >= 33V or short-term peak voltage of 37V < 1s
*2 power amplifier switched off, 5V output (sensor supply) is free, bus not connected
*3 No reverse polarity protection, the destruction limit is at overvoltage of >= 80V
*4 connector cable with max. possible cable cross-section, PWM frequency 32 kHz, ambient temperature 40 °C (t >40 °C derating), RMS current: 14.5 A → 11.8 Aeff no guarantee, since value is determined empirical, please consider the application notes to determine the continuous current
*5 default value

Additional technical data are available in mcManual.

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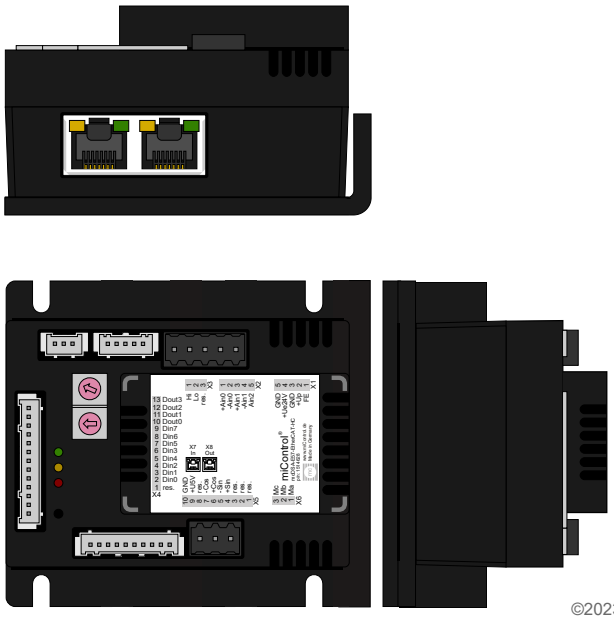
Scheme



Terminal assignment

X1	Supply	
1	FE	Functional earth
2	+Up	Power supply voltage
3	GND	Ground for power supply voltage
4	+Ue24V	Electronic supply voltage
5	GND	Ground for electronic supply voltage
X2	Analog inputs	
1	+Ain0	Analog input 0, plus
2	-Ain0	Analog input 0, minus
3	+Ain1	Analog input 1, plus
4	-Ain1	Analog input 1, minus
5	Ain2	Analog Input 2 (5V) / PT1000
X3	CAN bus	
1	CAN Hi	CAN High
2	CAN Lo	CAN Low
3	res.	Reserved
X4	Digital inputs/outputs	
1	res.	Reserved
2	Din0	Digital input 0
3	Din1	Digital input 1
4	Din2	Digital input 2
5	Din3	Digital input 3
6	Din4	Digital input 4
7	Din5	Digital input 5
8	Din6	Digital input 6
9	Din7	Digital input 7
10	Dout0	Digital output 0
11	Dout1	Digital output 1
12	Dout2	Digital output 2
13	Dout3	Digital output 3

X5	Encoder	
1	res.	Reserved
2	res.	Reserved
3	res.	Reserved
4	+Sin	Encoder, plus sine signal
5	-Sin	Encoder, minus sine signal
6	+Cos	Encoder, plus cosine signal
7	-Cos	Encoder, minus cosine signal
8	res.	Reserved
9	+U5V	5V output voltage for sensor supply Sensors: encoder
10	GND	Ground for sensor supply Notice: don't connect with system GND
X6	Motor	
1	Ma	Motor phase A
2	Mb	Motor phase B
3	Mc	Motor phase C
X7	EtherCAT - In port	
-	In	In
X8	EtherCAT - Out port	
-	Out	Out

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